

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

TROCKERS WORK

MATHEMATICAL INDUCTION & MATRICES

MATHEMATICAL INDUCTION

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NOTES

Definition: It is a method of proof in which a statement is proved for one step in a process, and it is shown that if the statement holds for that step, it holds for the next.

STEPS

- i. **Base Case/Initial Stage**
Show it is true for $n = 1, n = 2$ etc and give a conclusion of this stage.
- ii. **Assumption/Hypothesis Stage**
Suppose/ assume the statement is true for $n = k$.
- iii. **Thesis Stage**
Stating the result for $n = k + 1$.
- iv. **Proof Stage**
Proving true for $n = k + 1$. Use the thesis stage and the hypothesis stage to get the required result. Give a conclusion of this stage.
- v. **Conclusion Stage**
State four conditions clearly: $n = 1, n = k, n = k + 1$ and $n \in \mathbb{Z}^+$

Areas to consider

- Divisibility
- Series/Summations
- Matrices
- Integration
- Differentiation

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- Factorial Notation
- Composite Functions
- Binomial *etc*

DIVISIBILITY

Examples

1. Prove that $4^n + 5$ is divisible by 3 for all $n \in \mathbb{Z}^+$.
2. Use the principle of Mathematical Induction to verify that for n , any positive integer, $6^n - 1$ is divisible by 5.

Suggested Solutions

1. Let P_n denotes the statement that $4^n + 5$ is divisible by 3 for all $n \in \mathbb{Z}^+$.

When $n = 1$: $P_1 = 4^1 + 5 = 9$, which is divisible by 3 or we can say 9 is a multiple of 3. $\therefore P_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that P_n is true for $n = k$: **i.e.** $4^k + 5 = 3A \rightarrow 4^k = 3A - 5$.
(Assumption/Hypothesis Stage)

Then for $n = k + 1$: $P_{k+1} \rightarrow 4^{k+1} + 5 = 3B$. (Thesis Stage)

Proof

$$\begin{aligned}
 4^{k+1} + 5 &= 4^k \cdot 4^1 + 5 \\
 &= 4^1 \cdot 4^k + 5 \\
 &= 4(3A - 5) + 5 \\
 &= 4 \cdot 3A - 20 + 5 \\
 &= 4 \cdot 3A - 15 \\
 &= 3(4A - 5)
 \end{aligned}$$

$= 3B \sim B = 4A - 5$; which is true for $n = k + 1$.

$\therefore P_n$ is true for $n = k + 1$. (Proof Stage)

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Since P_n is true for $n = 1, n = k, n = k + 1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ **(Conclusion Stage)**

HINT

$6^n - 1$ is divisible by 5

$5^n - 1$ is divisible by 4

$4^n - 1$ is divisible by 3

$\vdots$

$k^n - 1$ is divisible by $(k - 1)$

SUMMATIONS/SERIES

Examples

1. Prove by induction that: $\sum_{r=1}^n r = \frac{n}{2}(n + 1)$ for all $n \in \mathbb{Z}^+$.

2. Prove by induction that:

$$1 + 4 + 7 + \dots + (3n - 2) = \frac{n(3n-1)}{2} \text{ for all positive integral values of } n.$$

Suggested Solutions

1. Let P_n denotes the statement that $\sum_{r=1}^n r = \frac{n}{2}(n + 1)$ for all $n \in \mathbb{Z}^+$.

When $n = 1$:

$$P_n \text{ LHS} = 1$$

$$P_n \text{ RHS} = \frac{1}{2}(1 + 1) = \frac{1}{2}(2) = 1 \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = 1 \therefore P_n$ is true for $n = 1$. **(Base Case/Initial Stage)**

Assuming that P_n is true for $n = k$: **i.e.** $\sum_{r=1}^k r = \frac{k}{2}(k + 1)$ **(Assumption/Hypothesis Stage)**

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Then for $n = k + 1$: $P_{k+1} \rightarrow \sum_{r=1}^{k+1} r = \frac{k+1}{2} [(k+1) + 1]$. (Thesis Stage)

Proof

Note:

$$a) \sum_{r=1}^k r = 1 + 2 + 3 + \dots + k$$

$$b) \sum_{r=1}^{k+1} r = 1 + 2 + 3 + \dots + k + (k+1) = \sum_{r=1}^k r + (k+1)$$

$$\begin{aligned} \sum_{r=1}^{k+1} r &= \sum_{r=1}^k r + (k+1) \\ &= \frac{k}{2}(k+1) + (k+1) \\ &= (k+1) \left(\frac{k}{2} + 1 \right) \\ &= (k+1) \left(\frac{k+2}{2} \right) \\ &= (k+1) \left[\frac{(k+1)+1}{2} \right] \\ &= \frac{k+1}{2} [(k+1) + 1], \text{ which is true for } n = k+1. \end{aligned}$$

$\therefore P_n$ is true for $n = k+1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k+1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

2. Let P_n denotes the statement that:

$$\text{For all positive integral values of } n, 1 + 4 + 7 + \dots + (3n - 2) = \frac{n(3n-1)}{2}$$

When $n = 1$:

$$P_n \text{ LHS} = 3(1) - 2 = 3 - 2 = 1$$

$$P_n \text{ RHS} = \frac{1[3(1)-1]}{2} = \frac{1(2)}{2} = \frac{2}{2} = 1 \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = 1 \therefore P_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that P_n is true for $n = k$: **i.e.** $1 + 4 + 7 + \dots + (3k - 2) = \frac{k(3k-1)}{2}$
(Assumption/Hypothesis Stage)

Then for $n = k + 1$: $P_{k+1} \rightarrow 1 + 4 + 7 + \dots + [3(k+1) - 2] = \frac{(k+1)[3(k+1)-1]}{2}$
(Thesis Stage)

Proof

Note:

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a) The summation of k terms $= 1 + 4 + 7 + \dots + (3k - 2)$

b) The summation of $(k+1)$ terms

$$= 1 + 4 + 7 + \dots + (3k - 2) + [3(k + 1) - 2]$$

$$= 1 + 4 + 7 + \dots + (3k - 2) + (3k - 2) \text{ (Bracket Expansion)}$$

$$= \text{the summation of } k \text{ terms} [1 + 4 + 7 + \dots + (3k - 2)] +$$

$$\text{the } (k + 1)^{\text{th}} \text{ term} [3k + 1]$$

$$1 + 4 + 7 + \dots + [3(k + 1) - 2] = 1 + 4 + 7 + \dots + (3k + 1)$$

$$= 1 + 4 + 7 + \dots + (3k - 2) + (3k + 1)$$

$$= \frac{k}{2}(3k - 1) + (3k + 1)$$

$$= \frac{k(3k-1)+2(3k+1)}{2}$$

$$= \frac{3k^2 - k + 6k + 2}{2}$$

$$= \frac{3k^2 + 5k + 2}{2}$$

$$= \frac{(k+1)(3k+2)}{2} \text{ (Factorisation)}$$

$$= \frac{(k+1)[(3k+3)-1]}{2}$$

$$= \frac{(k+1)[3(k+1)-1]}{2} \text{ which is true for } n = k + 1.$$

$\therefore P_n$ is true for $n = k + 1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k + 1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

MATRICES

Examples

1. Prove by Mathematical Induction that if $Z = \begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix}$, then

$$Z^n = \begin{pmatrix} n+1 & -n \\ n & 1-n \end{pmatrix} \text{ for all } n \in \mathbb{Z}^+.$$

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Suggested Solution

1. Let P_n denotes the statement that:

If $Z = \begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix}$, then $Z^n = \begin{pmatrix} n+1 & -n \\ n & 1-n \end{pmatrix}$ for all $n \in \mathbb{Z}^+$.

When $n = 1$:

$$P_n \text{ LHS} = Z^1 = Z = \begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix}.$$

$$P_n \text{ RHS} = \begin{pmatrix} 1+1 & -1 \\ 1 & 1-1 \end{pmatrix} = \begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix} \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = \begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix} \therefore P_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that P_n is true for $n = k$: i.e. $Z^k = \begin{pmatrix} k+1 & -k \\ k & 1-k \end{pmatrix}$ (Assumption/Hypothesis Stage)

Then for $n = k + 1$: $P_{k+1} \rightarrow Z^{k+1} = \begin{pmatrix} [(k+1)+1] & -(k+1) \\ k+1 & 1-(k+1) \end{pmatrix}$ (Thesis Stage)

Proof

Note:

$$a) Z^{k+1} = Z^k \cdot Z^1$$

$$Z^{k+1} = Z^k \cdot Z^1 = \begin{pmatrix} k+1 & -k \\ k & 1-k \end{pmatrix} \cdot \begin{pmatrix} 2 & -1 \\ 1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 2(k+1) - k & -1(k+1) + 0 \\ 2k + 1(1-k) & -k + 0 \end{pmatrix}$$

$$= \begin{pmatrix} 2k + 2 - k & -k - 1 \\ 2k + 1 - k & -k \end{pmatrix}$$

$$= \begin{pmatrix} k + 2 & -(k + 1) \\ k + 1 & -k + 1 - 1 \end{pmatrix}$$

$$= \begin{pmatrix} k + 2 & -(k + 1) \\ k + 1 & 1 - (k + 1) \end{pmatrix} \text{ which is true for } n = k + 1.$$

$\therefore P_n$ is true for $n = k + 1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k + 1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

INTEGRATION

Example

1. Use Induction to prove that $\int x^n = \frac{x^{n+1}}{n+1} + c$ for $n \in \mathbb{Z}^+$.

Suggested Solution

1. Let P_n denotes the statement that: $\int x^n = \frac{x^{n+1}}{n+1} + c$ for $n \in \mathbb{Z}^+$.

When $n = 1$:

$$P_n \text{ LHS} = \int x^1 dx = \frac{x^2}{2} + c$$

$$P_n \text{ RHS} = \frac{x^{1+1}}{1+1} + c = \frac{x^2}{2} + c \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = \frac{x^2}{2} + c \therefore P_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that P_n is true for $n = k$: i.e. $\int x^k = \frac{x^{k+1}}{k+1} + c$ (Assumption/Hypothesis Stage)

$$\text{Then for } n = k + 1: P_{k+1} \rightarrow \int x^{k+1} = \frac{x^{(k+1)+1}}{(k+1)+1} + c$$

(Thesis Stage)

Proof

Note:

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a) $\int x^{k+1} dx \equiv \int x^k \cdot x^1 dx$. Then use the method of integration by parts.
Choose u to be an expression which vanishes after performing 1 or more derivation.

$$\int x^{k+1} dx = \int x^k \cdot x^1 dx$$

$$\text{Let } u = x^1 \rightarrow \frac{du}{dx} = 1 \text{ and } \frac{dv}{dx} = x^k \rightarrow v = \frac{x^{k+1}}{k+1}$$

$$\text{Now use } \int u \frac{dv}{dx} = uv - \int v \frac{du}{dx} dx$$

$$\int x^{k+1} dx = x \frac{x^{k+1}}{k+1} - \int \frac{x^{k+1}}{k+1} (1) dx$$

$$= x \cdot \frac{x^{k+1}}{k+1} - \frac{x^{(k+1)+1}}{(k+1)[(k+1)+1]} + c$$

$$= \frac{x^{(k+1)+1}}{k+1} - \frac{x^{(k+1)+1}}{(k+1)[(k+1)+1]} + c \quad (\text{Since } a^b \cdot a^c = a^{b+c})$$

$$= \frac{x^{(k+1)+1}}{k+1} \left[1 - \frac{1}{[(k+1)+1]} \right] + c$$

$$= \frac{x^{(k+1)+1}}{k+1} \left[\frac{[(k+1)+1]}{[(k+1)+1]} - \frac{1}{[(k+1)+1]} \right] + c$$

$$= \frac{x^{(k+1)+1}}{k+1} \left[\frac{[(k+1)+1]-1}{[(k+1)+1]} \right] + c$$

$$= \frac{x^{(k+1)+1}}{k+1} \left[\frac{k+1}{[(k+1)+1]} \right] + c$$

$$= \frac{x^{(k+1)+1}}{(k+1)+1} + c ; \text{which is true for } n = k + 1.$$

$\therefore P_n$ is true for $n = k + 1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k + 1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

DIFFERENTIATION

Examples

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

1. Prove by Induction that $\frac{d(x^n)}{dx} = nx^{n-1}$.

2. Use Mathematical Induction to prove that if $y = xe^x$ then $\frac{d^n y}{dx^n} = (x+n)e^x$

Suggested Solutions

1. Let P_n denotes the statement that $\frac{d(x^n)}{dx} = nx^{n-1}$ for all $n \in \mathbb{Z}^+$.

When $n = 1$:

$$P_n \text{ LHS} = \frac{d(x^1)}{dx} = 1$$

$$P_n \text{ RHS} = 1 \cdot x^{1-1} = 1 \cdot x^0 = 1 \cdot 1 = 1 \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = 1 \therefore P_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that P_n is true for $n = k$: i.e. $\frac{d(x^k)}{dx} = kx^{k-1}$ (Assumption/Hypothesis Stage)

Then for $n = k + 1$: $P_{k+1} \rightarrow \frac{d(x^{k+1})}{dx} = (k+1)x^{(k+1)-1}$. (Thesis Stage)

Proof

Note:

a) $\frac{d(x^{k+1})}{dx} \equiv \frac{d(x^k \cdot x^1)}{dx}$. Then use the Product Rule.

$$\frac{d(x^{k+1})}{dx} = \frac{d(x^k \cdot x^1)}{dx}$$

$$\text{Let } v = x^1 \rightarrow \frac{dv}{dx} = 1 \text{ and } u = x^k \rightarrow \frac{du}{dx} = kx^{k-1}$$

$$\text{Now use } \frac{d(uv)}{dx} = u \frac{dv}{dx} + v \frac{du}{dx}.$$

$$\begin{aligned} \frac{d(x^{k+1})}{dx} &= x^k(1) + x^1(kx^{k-1}) \\ &= x^k(1) + kx^k \\ &= x^k(k+1) \\ &= (k+1)x^k \\ &= (k+1)x^{k+1-1} \end{aligned}$$

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$$= (k+1)x^{(k+1)-1}, \text{ which is true for } n = k+1.$$

$\therefore P_n$ is true for $n = k+1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k+1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

2. Let P_n denotes the statement that if $y = xe^x$ then $\frac{d^n y}{dx^n} = (x+n)e^x$ for all $n \in \mathbb{Z}^+$.

When $n = 1$:

$$P_n \text{ LHS} = \frac{d^1 y}{dx^1} = \frac{dy}{dx} = xe^x + e^x(1) = xe^x + e^x = (x+1)e^x$$

$$P_n \text{ RHS} = (x+1)e^x \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = 1 \therefore P_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that P_n is true for $n = k$: i.e. $\frac{d^k y}{dx^k} = (x+k)e^x$ (Assumption/Hypothesis Stage)

Then for $n = k+1$: $P_{k+1} \rightarrow \frac{d^{k+1} y}{dx^{k+1}} = [x + (k+1)]e^x$ (Thesis Stage)

Proof

Note:

$$b) \frac{d^{k+1} y}{dx^{k+1}} \equiv \frac{d^{k+1} y}{dx^{k+1}} \equiv \frac{d^k}{dx^k} \left[\frac{d(y)}{dx} \right] \equiv \frac{d}{dx} \left[\frac{d^k}{dx^k} \right]$$

$$\frac{d^{k+1} y}{dx^{k+1}} = \frac{d^k}{dx^k} \left[\frac{d(y)}{dx} \right]$$

$$= \frac{d}{dx} \left[\frac{d^k}{dx^k} \right]$$

$$= \frac{d}{dx} [(x+k)e^x] \text{ (Use the Product Rule)}$$

$$= (x+k)e^x + e^x(1)$$

$$= e^x[x + (k+1)]$$

$$= [x + (k+1)]e^x \text{ which is true for } n = k+1.$$

$\therefore P_n$ is true for $n = k+1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k+1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

FACTORIAL NOTATION

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

Example

Prove by Induction that $\sum_{r=1}^n r(r)! = (n+1)! - 1$ for all $n \in \mathbb{Z}^+$.

Suggested Solution

2. Let P_n denotes the statement that: $\sum_{r=1}^n r(r)! = (n+1)! - 1$ for all $n \in \mathbb{Z}^+$

When $n = 1$:

$$P_n \text{ LHS} = 1(1)! = 1 \times 1 = 1$$

$$P_n \text{ RHS} = (1 + 1)! - 1 = 2! - 1 = 2 \times 1 - 1 = 2 - 1 = 1 \equiv P_n \text{ LHS}$$

Since $P_n \text{ RHS} = P_n \text{ LHS} = 1 \therefore P_n$ is true for $n = 1$. **(Base Case/Initial Stage)**

Assuming that P_n is true for $n = k$: **i.e. $\sum_{r=1}^k r(r)! = (k+1)! - 1$ (Assumption/Hypothesis Stage)**

Then for $n = k + 1$: $P_{k+1} \rightarrow \sum_{r=1}^{k+1} r(r)! = [(k+1)+1]! - 1$
(Thesis Stage)

Proof

Note:

$$\text{a) } r! = r \times (r-1) \times (r-2) \times \dots \times (r-n); \quad r > n$$

$$\text{b) } (r+1)! = (r+1) \times r \times (r-1) \times (r-2) \times \dots \times (r-n); \quad r > n$$

$$\rightarrow (r+1)! = (r+1) \times r!$$

$$\rightarrow (r+2)! = (r+2) \times (r+1)!$$

$$\sum_{r=1}^{k+1} r(r)! = \sum_{r=1}^k r(r)! + (k+1)[(k+1)!]$$

$$= [(k+1)! - 1] + \{(k+1)(k+1)!\}$$

$$= \{(k+1)(k+1)!\} + (k+1)! - 1$$

$$= \{(k+1)[(k+1)!] + (k+1)! - 1\}$$

$$= \{(k+1)! [k+1+1]\} - 1$$

$$= \{(k+1)! \times (k+2)\} - 1$$

$$= (k+2)! - 1$$

$$= [(k+1)+1]! - 1; \text{ which is true for } n = k+1.$$

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$\therefore P_n$ is true for $n = k + 1$. (Proof Stage)

Since P_n is true for $n = 1, n = k, n = k + 1 \therefore P_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

COMPOSITE FUNCTIONS AND SEQUENCES

Examples

1. If $y = xe^x$, find:

i) $\frac{dy}{dx}$

ii) $\frac{d^2y}{dx^2}$

iii) $\frac{d^3y}{dx^3}$

iv) Suggest a formula for $\frac{d^ny}{dx^n}$

v) Prove your result in (iv) by Mathematical Induction.

2. Given that a sequence $U_1, U_2, U_3, \dots$ is defined by $U_1 = 3 ; (n \geq 1) \quad U_{n+1} = 3 - \frac{2}{U_n}$.

Prove by induction that for $n \in \mathbb{Z}^+$, $U_n = \frac{2^{n+1} - 1}{2^n - 1}$

Suggested Solutions

1. i) $\frac{dy}{dx} = xe^x + e^x (1) = xe^x + e^x = (x + 1)e^x$ (Use the Product Rule)

ii) $\frac{d^2y}{dx^2} = \frac{d}{dx} \left(\frac{dy}{dx} \right) = [xe^x + e^x (1)] + e^x$
 $= xe^x + e^x + e^x$
 $= (x + 2)e^x$

iii) $\frac{d^3y}{dx^3} = \frac{d}{dx} \left(\frac{d^2y}{dx^2} \right) = [xe^x + e^x (1)] + e^x + e^x$
 $= xe^x + e^x + e^x + e^x$
 $= (x + 3)e^x$

iv) $\frac{d^ny}{dx^n} = (x + n)e^x$

v) The proof has been worked out on the differentiation section.

2. $U_n = \frac{2^{n+1} - 1}{2^n - 1}$ for all $n \in \mathbb{Z}^+$.

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When $n = 1$:

$$U_1 = \frac{2^{1+1}-1}{2^1-1} = \frac{2^2-1}{2^1-1} = \frac{4-1}{2-1} = 3 \equiv \text{the given condition } U_1 = 3$$

$\therefore U_n$ is true for $n = 1$. (Base Case/Initial Stage)

Assuming that U is true for $n = k$: i.e. $U_k = \frac{2^{k+1}-1}{2^k-1}$ (Assumption/Hypothesis Stage)

Then for $n = k + 1$: $U_{k+1} = \frac{2^{(k+1)+1}-1}{2^{k+1}-1}$ (Thesis Stage)

Proof

$$\begin{aligned} U_{n+1} &= 3 - \frac{2}{U_n} \\ \rightarrow U_{n+1} &= 3 - \frac{2}{\frac{2^{k+1}-1}{2^k-1}} \\ \rightarrow U_{n+1} &= 3 - \frac{2(2^k-1)}{2^{k+1}-1} \\ \rightarrow U_{n+1} &= \frac{3(2^{k+1}-1) - 2(2^k-1)}{2^{k+1}-1} \\ \rightarrow U_{n+1} &= \frac{3 \times 2^{k+1} - 3 - 2 \times 2^k + 2}{2^{k+1}-1} \\ \rightarrow U_{n+1} &= \frac{3 \times 2^{k+1} - 3 - 2^{k+1} - 2}{2^{k+1}-1} \quad (\text{Since } a^b \cdot a^c = a^{b+c}) \\ \rightarrow U_{n+1} &= \frac{(2 \times 2^{k+1}) - 1}{2^{k+1}-1} \\ \rightarrow U_{n+1} &= \frac{2^{k+2} - 1}{2^{k+1}-1} \quad (\text{Since } a^b \cdot a^c = a^{b+c}) \\ \rightarrow U_{n+1} &= \frac{2^{(k+1)+1}-1}{2^{k+1}-1}; \text{ which is true for } n = k + 1. \end{aligned}$$

U is true for $n = k + 1$. (Proof Stage)

Since U_n is true for $n = 1, n = k, n = k + 1 \therefore U_n$ is also true for $n \in \mathbb{Z}^+$ (Conclusion Stage)

PRACTICE QUESTIONS

1. Prove that $5^n + 2(11^n)$ is a multiple of 3 for all positive integers of n .
2. Prove by Mathematical Induction that $n^5 - n$ is a multiple of 5 for all natural numbers n .
3. Prove that $5^{6n} + 2^{3n+1} - 1$ is a multiple of 7.
4. Prove that $6^n + 8^n$ is a multiple of 7, when n is odd.

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5. Prove by Mathematical Induction that $n^3 - n$ is divisible by 6 for all natural numbers n .

6. Prove by induction that: $1 + 2 + 3 + \dots + n = \frac{n}{2}(n + 1)$ for any $n \geq 1$.

7. Prove by induction that:

$$\sum_{r=1}^n (r^3 - r) = \frac{1}{4}n(n-1)(n+1)(n+2) \text{ for all } n \in \mathbb{Z}^+$$

Hence Evaluate

$$\sum_{r=3}^{50} (r^3 - r).$$

8. Prove by induction that:

$$\sum_{r=1}^n r^2 = \frac{1}{6}n(n+1)(2n+1) \text{ for all } n \in \mathbb{Z}^+$$

9. Prove by induction that:

$$1^2 + 2^2 + 3^2 + \dots + n^2 = \frac{1}{6}n(n+1)(2n+1) \text{ for all } n \in \mathbb{Z}^+$$

10. Use Mathematical Induction to prove that:

$$\sum_{r=1}^n = \frac{1}{4}n^2(n+1)^2 \text{ for all } n \in \mathbb{Z}^+$$

11. Use Mathematical Induction to prove that:

$$1^3 + 2^3 + 3^3 + \dots + n^3 = \frac{1}{4}n^2(n+1)^2 \text{ for all } n \in \mathbb{Z}^+$$

12. Prove by induction that for any $n \geq 1$;

$$\sum_{r=1}^n (3r-2)^2 = \frac{1}{2}n(6n^2 - 3n - 1).$$

13. Prove by induction that for any $n \geq 1$;

$$1 + 4 + 7 + \dots + (3n-2)^2 = \frac{1}{2}n(6n^2 - 3n - 1)$$

14. Prove by induction that:

$$\sum_{r=1}^n (2r-1) = n^2 \text{ for all positive integral values of } n.$$

15. Prove by induction that: $\sum_{r=1}^n (3r-2) = \frac{n}{2}(3n-1)$ for all $n \in \mathbb{Z}^+$

16. Prove by Mathematical Induction that if $P = \begin{pmatrix} 2 & a \\ 0 & 1 \end{pmatrix}$, then

$$P^n = \begin{pmatrix} 2^n & (2^n - 1)a \\ 0 & 1 \end{pmatrix} \text{ for all } n \in \mathbb{Z}^+.$$

17. Prove by induction that $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix}^{2n+1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix}.$

18. Prove by Mathematical Induction that if $Q = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$, then

$$Q^n = \begin{pmatrix} 1 & n & \frac{n}{2}(n+1) \\ 0 & 1 & n \\ 0 & 0 & 1 \end{pmatrix} \text{ for all } n \in \mathbb{Z}^+.$$

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

19. Prove by Mathematical Induction that $\begin{pmatrix} 1 & a \\ 0 & a \end{pmatrix}^n = \begin{pmatrix} 1 & \frac{a^{n+1}-1}{a-1} \\ 0 & a^n \end{pmatrix}$ for all $n \in \mathbb{Z}^+$.

20. Prove by Mathematical Induction that if $A = \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$, then

$$A^n = \begin{pmatrix} 1 & 3n \\ 0 & 1 \end{pmatrix} \text{ for all } n \in \mathbb{Z}^+.$$

21. Prove by Mathematical Induction that if $X = \begin{pmatrix} 3 & -1 \\ 4 & -1 \end{pmatrix}$, then

$$X^n = \begin{pmatrix} 2n+1 & -n \\ 4n & 1-2n \end{pmatrix} \text{ for all } n \in \mathbb{Z}^+.$$

22. Prove by Mathematical Induction that if $B = \begin{pmatrix} 1+\cos\theta & \sin\theta \\ \sin\theta & 1-\cos\theta \end{pmatrix}$, then

$$B^{n+1} = 2^n \times B \text{ for all } n \in \mathbb{Z}^+.$$

23. Use Mathematical Induction to prove that if $y = \frac{1}{2x+1}$ then:

$$\frac{d^n y}{dx^n} = \frac{(-2)^n n!}{(2x+1)^{n+1}}$$

24. Use Mathematical Induction to prove that if $y = \cos x$ then $\frac{d^n y}{dx^n} = \cos\left(x + \frac{n\pi}{2}\right)$

25. Prove by Induction that $\frac{d^n(x^m)}{dx^n} = \frac{m!}{(m-n)!} x^{m-n}; \quad m \geq n$.

26. If $\frac{dy}{dx} = 2xy - 1$, show by Induction that $\frac{d^{n+2}y}{dx^{n+2}} = 2(n+1) \frac{d^n y}{dx^n} + 2x \frac{d^{n+1}y}{dx^{n+1}}$.

27. Prove by Induction that if $y = \sin ax$ then $\frac{d^n y}{dx^n} = a^n \sin\left(x + \frac{n\pi}{2}\right)$

28. Given that a sequence $U_1, U_2, U_3, \dots$ is defined by $U_1 = 5; (n \geq 1) \quad U_{n+1} = 2U_n + 1$.

Prove by induction that for $n \in \mathbb{Z}^+, U_n = 3 \times 2^n - 1$

29. Given that $f(x) = \frac{x}{x+1}$, find:

i) $f \cdot f(x)$

ii) $f \cdot [f \cdot f(x)]$

iii) Suggest a formula for $f^n(x)$

iv) Prove the result in (iii) by Induction.

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MATRICES

NOTES

- A matrix is a rectangular array of numbers.
- Each entry in the matrix is called an element.
- Matrices are classified by the number of rows and columns that they have.
- Let A be the matrix with m rows and n columns then A called an $(m \times n)$ matrix said m by n .
- $(m$ by $n)$ is called the order of matrix A .
- If $(m = n)$ then the matrix is called a square matrix.
- The element of A can be denoted by a_{ij} .
- i is the row in which the element is found and j represent the column in which the element is found

Example

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

1. Given that $T = \begin{pmatrix} 1 & -6 & 3 \\ 2 & 5 & -1 \\ 0 & -10 & 4 \end{pmatrix}$

- State the order of T .
- List the elements a_{11} and a_{32} .

Suggested Solutions

- Since T has 3 rows and 3 columns thus it is of order (3×3) .
 - $a_{11} = 1$ and $a_{32} = -10$.

MATRICES - ADDITION AND SUBTRACTION

NOTES

- Addition and subtraction of matrices is defined if and only if the matrices are of the same order.
- The sum/difference of matrices A and B is the matrix obtained by adding/subtracting the elements in corresponding positions of matrices A and B .
- If you multiply the matrix A by a scalar m then every element of A is multiplied by m .

Note: If A and B are matrices then the following results are true:

- $A + B = B + A$
- $A - B \neq B - A$ but $A - B = -(B - A)$

Example

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

1. Given that $A = \begin{pmatrix} 5 & -2 & 4 \\ 3 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix}$ and $B = \begin{pmatrix} 4 & 0 & 0 \\ -2 & 6 & 2 \\ 0 & -2 & 4 \end{pmatrix}$

i) Prove that $A + B = B + A$ and $A - B \neq B - A$

ii) Find $4A - \frac{1}{2}B$

Suggested Solutions

$$1. \text{ i) } A + B = \begin{pmatrix} 5 & -2 & 4 \\ 3 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix} + \begin{pmatrix} 4 & 0 & 0 \\ -2 & 6 & 2 \\ 0 & -2 & 4 \end{pmatrix} = \begin{pmatrix} 9 & -2 & 4 \\ 1 & 7 & 1 \\ 1 & -2 & 3 \end{pmatrix}$$

$$B + A = \begin{pmatrix} 4 & 0 & 0 \\ -2 & 6 & 2 \\ 0 & -2 & 4 \end{pmatrix} + \begin{pmatrix} 5 & -2 & 4 \\ 3 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 9 & -2 & 4 \\ 1 & 7 & 1 \\ 1 & -2 & 3 \end{pmatrix}$$

$$\text{Since } A + B = \begin{pmatrix} 9 & -2 & 4 \\ 1 & 7 & 1 \\ 1 & -2 & 3 \end{pmatrix} \text{ and } B + A = \begin{pmatrix} 9 & -2 & 4 \\ 1 & 7 & 1 \\ 1 & -2 & 3 \end{pmatrix} \therefore A + B = B + A$$

$$\text{Now } A - B = \begin{pmatrix} 5 & -2 & 4 \\ 3 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix} - \begin{pmatrix} 4 & 0 & 0 \\ -2 & 6 & 2 \\ 0 & -2 & 4 \end{pmatrix} = \begin{pmatrix} 1 & -2 & 4 \\ 5 & -5 & -3 \\ 1 & 2 & -5 \end{pmatrix}$$

$$B - A = \begin{pmatrix} 4 & 0 & 0 \\ -2 & 6 & 2 \\ 0 & -2 & 4 \end{pmatrix} - \begin{pmatrix} 5 & -2 & 4 \\ 3 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & 2 & -4 \\ -5 & 5 & 3 \\ -1 & -2 & 5 \end{pmatrix}$$

$$= -\begin{pmatrix} 1 & -2 & 4 \\ 5 & -5 & -3 \\ 1 & 2 & -5 \end{pmatrix} \neq A - B \text{ but } -(A - B) \text{ (proven)}$$

$$\text{ii) } 4A - \frac{1}{2}B = 4\begin{pmatrix} 5 & -2 & 4 \\ 3 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix} - \frac{1}{2}\begin{pmatrix} 4 & 0 & 0 \\ -2 & 6 & 2 \\ 0 & -2 & 4 \end{pmatrix}$$

$$= \begin{pmatrix} 20 & -8 & 16 \\ 12 & 4 & -4 \\ 4 & 0 & -4 \end{pmatrix} - \begin{pmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ 0 & -1 & 2 \end{pmatrix}$$

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$$= \begin{pmatrix} 18 & -8 & 16 \\ 13 & 1 & -5 \\ 4 & 1 & -6 \end{pmatrix}$$

MATRICES - MULTIPLICATION

NOTES

- Let A and B be matrices. Then the multiplication of A and B is possible if and only if then number of *columns* of A is equal to the number of *rows* of B .
- If A is an $(m \times n)$ matrix and B is an $(x \times y)$ matrix, then the product AB exist if and only if $n = x$.
- AB will be an $(m \times y)$ matrix.

Note:

- The product $AB \neq BA$.

Example

1. Given that $A = \begin{pmatrix} -1 & 1 & 0 \\ 0 & 2 & -2 \\ 1 & 0 & -1 \end{pmatrix}$ and $B = \begin{pmatrix} 2 & 0 & 1 \\ -2 & 0 & 2 \\ 0 & -1 & 1 \end{pmatrix}$

- Prove that $AB \neq BA$
- Find A^2

Suggested Solutions

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

$$\begin{aligned}
 1. \text{ i) } AB &= \begin{pmatrix} -1 & 1 & 0 \\ 0 & 2 & -2 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 1 \\ -2 & 0 & 2 \\ 0 & -1 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} (-1 \times 2) + (1 \times -2) + (0 \times 0) & (-1 \times 0) + (1 \times 0) + (0 \times -1) & (-1 \times 1) + (1 \times 2) + (0 \times 1) \\ (0 \times 2) + (2 \times -2) + (-2 \times 0) & (0 \times 0) + (2 \times 0) + (-2 \times -1) & (0 \times 1) + (2 \times 2) + (-2 \times 1) \\ (1 \times 2) + (0 \times -2) + (-1 \times 0) & (1 \times 0) + (0 \times 0) + (-1 \times -1) & (1 \times 1) + (0 \times 2) + (-1 \times 1) \end{pmatrix} \\
 &= \begin{pmatrix} -2 - 2 + 0 & 0 + 0 + 0 & -1 + 2 + 0 \\ 0 - 4 + 0 & 0 + 0 + 2 & 0 + 4 - 2 \\ 2 + 0 + 0 & 0 + 0 + 1 & 1 + 0 - 1 \end{pmatrix} \\
 &= \begin{pmatrix} -4 & 0 & 1 \\ -4 & 2 & 2 \\ 2 & 1 & 0 \end{pmatrix} \\
 \text{and } BA &= \begin{pmatrix} 2 & 0 & 1 \\ -2 & 0 & 2 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} -1 & 1 & 0 \\ 0 & 2 & -2 \\ 1 & 0 & -1 \end{pmatrix} \\
 &= \begin{pmatrix} (-2 \times -1) + (0 \times 0) + (1 \times 1) & (-2 \times 1) + (0 \times 2) + (1 \times 0) & (-2 \times 0) + (0 \times -2) + (1 \times -1) \\ (-2 \times -1) + (0 \times 0) + (2 \times 1) & (-2 \times 1) + (0 \times 2) + (2 \times 0) & (-2 \times 0) + (0 \times -2) + (2 \times -1) \\ (0 \times -1) + (-1 \times 0) + (1 \times 1) & (0 \times 1) + (-1 \times 2) + (1 \times 0) & (0 \times 0) + (-1 \times -2) + (1 \times -1) \end{pmatrix} \\
 &= \begin{pmatrix} 2 + 0 + 1 & -2 + 0 + 0 & 0 + 0 - 1 \\ 2 + 0 + 2 & -2 + 0 + 0 & 0 + 0 - 2 \\ 0 + 0 + 1 & 0 - 2 + 0 & 0 + 2 - 1 \end{pmatrix} \\
 &= \begin{pmatrix} 3 & -2 & -1 \\ 4 & -2 & -2 \\ 1 & -2 & 1 \end{pmatrix} \neq AB \text{ (proven).}
 \end{aligned}$$

$$\begin{aligned}
 \text{ii) } A^2 &= \begin{pmatrix} -1 & 1 & 0 \\ 0 & 2 & -2 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} -1 & 1 & 0 \\ 0 & 2 & -2 \\ 1 & 0 & -1 \end{pmatrix} \\
 &= \begin{pmatrix} 1 + 0 + 0 & -1 + 2 + 0 & 0 - 2 + 0 \\ 0 + 0 - 2 & 0 + 4 + 0 & 0 - 4 + 2 \\ -1 + 0 - 1 & 1 + 0 + 0 & 0 + 0 + 1 \end{pmatrix} \\
 &= \begin{pmatrix} 1 & 1 & -2 \\ -2 & 4 & -2 \\ -2 & 1 & -1 \end{pmatrix}
 \end{aligned}$$

SPECIAL MATRICES

NOTES

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

- An Identity Matrix is a special matrix in which if you pre-multiply or post-multiply any matrix A by it, A remains unchanged. i.e. $I_n A = A I_n = A$
- The identity matrix of an $(n \times n)$ is represented by I_n where n is the number of rows or columns since it is a square matrix

• The general matrix of an identity matrix is given by: $I_n = \begin{pmatrix} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & & \vdots & 0 \\ \vdots & 0 & \ddots & 0 & \vdots \\ 0 & \vdots & \dots & 0 & 1 \\ 0 & 0 & \dots & \dots & 0 & 1 \end{pmatrix}$

- For example: $I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ is an identity matrix for a (2×2) matrix and

$I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ is an identity matrix for a (3×3) matrix.

- The Zero Matrix is a matrix whose elements are all Zeroes.
- The Zero Matrix is represented by Z e.g. a (3×3) matrix is given by

$I_3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

- Adding Z to any matrix, say A leaves A unchanged and pre-multiplying or post-multiplying Z with A , leaves Z unchanged
- i.e. $Z + A = A + Z = A$ and $ZA = AZ = Z$

MATRICES - TRANSPOSING

NOTES

- The transpose of a matrix A is found by inter-changing rows and columns of matrix A . i.e.
- The transpose of matrix A is represented as A^T or A'
- If $A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$ then $A^T = \begin{pmatrix} a & d & g \\ b & e & h \\ c & f & i \end{pmatrix}$.
- The elements in the diagonal column does not change i.e. a, e and i

Examples

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

1. Given that $A = \begin{pmatrix} 2 & 5 & 11 \\ -8 & 0 & 7 \\ 3 & 10 & 9 \end{pmatrix}$; find A' .

Suggested Solution

1. $A' = \begin{pmatrix} 2 & -8 & 3 \\ 5 & 0 & 10 \\ 11 & 7 & 9 \end{pmatrix}$

MATRICES - DETERMINANTS

NOTES

- Determinants play a major role in finding the inverse of the matrix and also in solving a system of linear equations.

DETERMINANTS – 2X2 MATRICES

NOTES

- Suppose A is any (2×2) Matrix such that $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ then the determinant of A can be written as $|A|$ or $\det(A)$ or $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$.

Examples

1. Given that $A = \begin{pmatrix} 6 & -1 \\ 4 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$; find the determinant of A and the determinant of B .

Suggested Solutions

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

1. $\det(A) = ad - bc = 6(1) - (-1 \times 4) = 6 + 4 = 10.$
 $\det(B) = ad - bc = \cos\theta(\cos\theta) - (\sin\theta \times -\sin\theta)$
 $= \cos^2\theta + \sin^2\theta \equiv 1$

DETERMINANTS – 3X3 MATRICES

NOTES

- Suppose A is any (3×3) Matrix such that $A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$ then the

determinant of A can be written as $|A|$ or $\det(A)$ or $\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix}$

- Several techniques can be employed to find the determinants for (3×3) Matrices i.e.
 - i) The Basket weave formula
 - ii) The method of cofactors
 - iii) Multiplying A by its Adjoint Matrix.

DETERMINANTS – The Basket Weave Formula

NOTES

- We add the first and the second columns of A as follows:

$$\det(A) = \begin{vmatrix} a & b & c & a & b \\ d & e & f & d & e \\ g & h & i & g & h \end{vmatrix}$$

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- $\det(A) = \text{"sum of products along the } \nearrow \text{ diagonals"} - \text{"sum of products along } \searrow \text{ diagonals"}$
- $= aei + bfg + cdh - gec - hfa - idb$

DETERMINANTS – The Method of Cofactors

NOTES

- This method can be applied to all $(n \times n)$ Matrices.
- Suppose A is any (3×3) Matrix such that $A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$ then to find the determinant you choose a row or column to work with; for instance we are going to choose the row containing the elements $(a \ b \ c)$.
- When choosing the row or column to work with, choose the one with 1 or more zeroes because it is easy to simplify.
- We multiply each element a_{ij} in the chosen row/column by the determinant of a (2×2) matrix which remains when the row and the column containing a_{ij} are deleted from A . This is illustrated as follows:
 - $\det(A) = (-1)^{i+j} a \begin{vmatrix} e & f \\ h & i \end{vmatrix} + (-1)^{i+j} b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + (-1)^{i+j} c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$
 - ' i ' represent the row in which the element a_{ij} from the chosen row/column is found
 - ' j ' represent the column in which the element a_{ij} from the chosen row/column is found
- If $(i + j)$ is even then a_{ij} is even and if $(i + j)$ is odd then a_{ij} is odd. For example:
 - i. $(-1)^{1+1} a = (-1)^2 a = +a$
 - ii. $(-1)^{2+1} b = (-1)^3 b = -b$
 - iii. $(-1)^{3+1} c = (-1)^4 c = +c$
- $\therefore \det(A) = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$.

Examples

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

2. Given that $A = \begin{pmatrix} 3 & 1 & 1 \\ 2 & -1 & 2 \\ 1 & 1 & -2 \end{pmatrix}$; find the determinant of A using the both methods.

Suggested Solutions

a. The Method of Cofactors

$$\begin{aligned}
 1. \det(A) &= 3 \begin{vmatrix} -1 & 2 \\ 1 & -2 \end{vmatrix} - 1 \begin{vmatrix} 2 & 2 \\ 1 & -2 \end{vmatrix} + 1 \begin{vmatrix} 2 & -1 \\ 1 & 1 \end{vmatrix} \\
 &= 3(2 - 2) - 1(-4 - 2) + 1(2 - -1) \\
 &= 3(0) - 1(-6) + 1(3) \\
 &= 0 + 6 + 3 \\
 &= 9
 \end{aligned}$$

b. The Basket Weave Formula

$$1. \det(A) = \begin{vmatrix} 3 & 1 & 1 & 3 & 1 \\ 2 & -1 & 2 & 2 & -1 \\ 1 & 1 & -2 & 1 & 1 \end{vmatrix}$$

$$\begin{aligned}
 &= (3 \times -1 \times -2) + (1 \times 2 \times 1) + (1 \times 2 \times 1) - (1 \times -1 \times 1) - (1 \times 2 \times 3) - (-2 \times 2 \times 1) \\
 &= (6) + (2) + (2) - (-1) - (6) - (-4) \\
 &= 10 + 1 - 6 + 4 \\
 &= 5 + 4 \\
 &= 9
 \end{aligned}$$

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INVERSE OF MATRICES

2x2 MATRICES

NOTES

- If $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then $A^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$; where $ad - bc$ is the determinant.
- $AA^{-1} = A^{-1}A = I$ where I is the identity matrix.
- If $ad = bc$ then $\frac{1}{ad-bc} = \frac{1}{0}$, which is not defined and in this case, A^{-1} does not exist and the matrix A is described as singular or non-invertible.
- If A^{-1} exist, then the matrix A is described as being non-singular or invertible.
- If we have two matrices A and B then $(AB)^{-1} = B^{-1}A^{-1}$

Examples

1. Find the inverse of $A = \begin{pmatrix} 3 & -4 \\ 2 & 1 \end{pmatrix}$

Suggested Solutions

1. $\text{Det}(A) = ad - bc = 3(1) - 2(-4) = 3 + 8 = 11$
Now $A^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \frac{1}{11} \begin{pmatrix} 1 & -(-4) \\ -2 & 3 \end{pmatrix} = \frac{1}{11} \begin{pmatrix} 1 & 4 \\ -2 & 3 \end{pmatrix}$.

3x3 MATRICES

NOTES

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

- For any $(n \times n)$ matrix the Adjoint and determinant are defined and satisfy:
 $A \times adj(A) = adj(A) \times A = \det(A) \times I_n$
- If $\det(A) \neq 0$ then A is said to be invertible and A^{-1} exist i.e.
 $A^{-1} = \frac{1}{\det(A)} \times adj(A).$
- If $\det(A) = 0$ then A is said to be non-invertible and A^{-1} does not exist.

Examples

1. Find the inverse of $A = \begin{pmatrix} 2 & 1 & 0 \\ 3 & -1 & 4 \\ 1 & 1 & 2 \end{pmatrix}.$

Suggested Solutions

1. We begin by finding the Minors of matrix A , followed by the Cofactors of matrix A then the Adjoint and finally A^{-1} .

i. The Matrix of Minors

- For each of every element of matrix A , a_{ij} , we define the minor, M_{ij} of a_{ij} , to be the determinant of the 2×2 matrix which remains when the row and the column containing a_{ij} is deleted from A .
- ' i ' represent the row in which the element a_{ij} is found and ' j ' represent the column in which the element a_{ij} is found

$$M = \begin{pmatrix} M_{11} & M_{12} & M_{13} \\ M_{21} & M_{22} & M_{23} \\ M_{31} & M_{32} & M_{33} \end{pmatrix}$$

$$M_{11} = \begin{vmatrix} -1 & 4 \\ 1 & 2 \end{vmatrix} = (-1 \times 2) - (1 \times 4) = -2 - 4 = -6$$

$$M_{12} = \begin{vmatrix} 3 & 4 \\ 1 & 2 \end{vmatrix} = (3 \times 2) - (1 \times 4) = 6 - 4 = 2$$

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

$$M_{13} = \begin{vmatrix} 3 & -1 \\ 1 & 1 \end{vmatrix} = (3 \times 1) - (-1 \times 1) = 3 + 1 = 4$$

$$M_{21} = \begin{vmatrix} 1 & 0 \\ 1 & 2 \end{vmatrix} = (1 \times 2) - (1 \times 0) = 2 - 0 = 2$$

$$M_{22} = \begin{vmatrix} 2 & 0 \\ 1 & 2 \end{vmatrix} = (2 \times 2) - (1 \times 0) = 4 - 0 = 4$$

$$M_{23} = \begin{vmatrix} 2 & 1 \\ 1 & 1 \end{vmatrix} = (2 \times 1) - (1 \times 1) = 2 - 1 = 1$$

$$M_{31} = \begin{vmatrix} 1 & 0 \\ -1 & 4 \end{vmatrix} = (1 \times 4) - (0 \times -1) = 4 - 0 = 4$$

$$M_{32} = \begin{vmatrix} 2 & 0 \\ 3 & 4 \end{vmatrix} = (2 \times 4) - (0 \times 3) = 8 - 0 = 8$$

$$M_{33} = \begin{vmatrix} 2 & 1 \\ 3 & -1 \end{vmatrix} = (2 \times -1) - (1 \times 3) = -2 - 3 = -5$$

$$\therefore M = \begin{pmatrix} -6 & 2 & 4 \\ 2 & 4 & 1 \\ 4 & 8 & -5 \end{pmatrix}$$

ii. The Matrix of Minors

- We define the cofactors of A as follows:

a. $C_{ij} = M_{ij}$ if $i + j$ is even.

b. $C_{ij} = -M_{ij}$ if $i + j$ is odd.

- Hence the following pattern of signs is produced; $\begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$.

- Now C is the matrix of cofactors of matrix A and it differs from matrix M by the above pattern of signs

$$C = \begin{pmatrix} +(-6) & -(2) & +(4) \\ -(2) & +(4) & -(1) \\ +(4) & -(8) & +(-5) \end{pmatrix} = \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -1 \\ 4 & -8 & -5 \end{pmatrix}$$

iii. The Adjoint

- The Adjoint of A is C' or C^T , which is the transpose of the matrix of cofactors of A .

$$Adj(A) = \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix}$$

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

iv. The Inverse

- We now compute $A \times Adj(A)$

$$\begin{aligned}
 A \times Adj(A) &= \begin{pmatrix} 2 & 1 & 0 \\ 3 & -1 & 4 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix} \\
 &= \begin{pmatrix} (2 \times -6) + (1 \times -2) + (0 \times 4) & (2 \times -2) + (1 \times 4) + (0 \times -1) & (2 \times 4) + (1 \times -8) + (0 \times -5) \\ (3 \times -6) + (-1 \times -2) + (4 \times 4) & (3 \times -2) + (-1 \times 4) + (4 \times -1) & (3 \times 4) + (-1 \times -8) + (4 \times -5) \\ (1 \times -6) + (1 \times -2) + (2 \times 4) & (1 \times -2) + (1 \times 4) + (2 \times -1) & (1 \times 4) + (1 \times -8) + (2 \times -5) \end{pmatrix} \\
 &= \begin{pmatrix} -12 - 2 + 0 & -4 + 4 + 0 & 8 - 8 + 0 \\ -18 + 4 + 16 & -6 - 4 - 4 & 12 + 8 - 20 \\ -6 - 2 + 8 & -2 + 4 - 2 & 4 - 8 - 10 \end{pmatrix} \\
 &= \begin{pmatrix} -14 & 0 & 0 \\ 0 & -14 & 0 \\ 0 & 0 & -14 \end{pmatrix}
 \end{aligned}$$

- Now $A \times adj(A) = adj(A) \times A = \det(A) \times I_n$

$$\text{Hence } \begin{pmatrix} -14 & 0 & 0 \\ 0 & -14 & 0 \\ 0 & 0 & -14 \end{pmatrix} = -\frac{1}{14} \times \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = -\frac{1}{14} \times I_n.$$

$$\therefore \det(A) = -14$$

- N.B. This is the other method of computing the determinant of any $(n \times n)$ matrix.

$$\text{Now } A^{-1} = \frac{1}{\det(A)} \times Adj(A) = -\frac{1}{14} \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix}.$$

MATRICES -Solving Systems of Linear Equations

2x2 MATRICES

NOTES

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

- In general if:

$$ax + by = e$$

$$cx + dy = f$$

- Then the equations can be re-written as follows:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} e \\ f \end{pmatrix}$$

- Now we find the inverse of a 2×2 matrix and pre-multiply both sides of the equations by it, i.e.

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} \begin{pmatrix} e \\ f \end{pmatrix}$$

$$\rightarrow I_2 \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} \begin{pmatrix} e \\ f \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} \begin{pmatrix} e \\ f \end{pmatrix}$$

Examples

1. Use the matrix method to solve the following system of linear equations.

$$2x - y = 1$$

$$x + 3y = 4$$

Suggested Solutions

1. The equations can be written in matrix form as follows:

$$\begin{pmatrix} 2 & -1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\text{Now let } A = \begin{pmatrix} 2 & -1 \\ 1 & 3 \end{pmatrix}.$$

$$\text{Det}(A) = ad - bc = 2(3) - 1(-1) = 6 + 1 = 7$$

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

$$\text{Now } A^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 3 & -(-1) \\ -1 & 2 \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix}.$$

Pre-multiplying both sides by the inverse yields

$$\frac{1}{7} \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\rightarrow I \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{7} \begin{bmatrix} (3 \times 1) + (1 \times 4) \\ (-1 \times 1) + (2 \times 4) \end{bmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 7 \\ 7 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$\therefore x = 1$ and $y = 1$.

3x3 MATRICES

NOTES

- In general if:

$$ax + by + cz = m$$

$$dx + ey + fz = n$$

$$gx + hy + iz = o$$

- Then the equations can be re-written as follows:

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} m \\ n \\ o \end{pmatrix}$$

- Now we find the inverse of a 3×3 matrix and pre-multiply both sides of the equations by it, i.e.

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}^{-1} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}^{-1} \begin{pmatrix} m \\ n \\ o \end{pmatrix}$$

$$\rightarrow I_3 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}^{-1} \begin{pmatrix} m \\ n \\ o \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}^{-1} \begin{pmatrix} m \\ n \\ o \end{pmatrix}$$

Examples

1. Solve the following system of linear equations.

$$2x + y = 1$$

$$3x - y + 4z = 2$$

$$x + y + 2z = -1$$

Suggested Solutions

2. The equations can be written in matrix form as follows:

$$\begin{pmatrix} 2 & 1 & 0 \\ 3 & -1 & 4 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$

$$\text{Now let } A = \begin{pmatrix} 2 & 1 & 0 \\ 3 & -1 & 4 \\ 1 & 1 & 2 \end{pmatrix} \text{ then } A^{-1} = -\frac{1}{14} \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix}$$

(see the whole solution under the inverse for 3X3 matrices)

Pre-multiplying both sides by this inverse:

$$\rightarrow -\frac{1}{14} \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix} \begin{pmatrix} 2 & 1 & 0 \\ 3 & -1 & 4 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -\frac{1}{14} \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$

“Do not worry too much about your difficulties in Mathematics, I can assure you that mine are still greater.” Albert Einstein.

$$\rightarrow I_3 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -\frac{1}{14} \begin{pmatrix} -6 & -2 & 4 \\ -2 & 4 & -8 \\ 4 & -1 & -5 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -\frac{1}{14} \begin{bmatrix} (-6 \times 1) + (-2 \times 2) + (4 \times -1) \\ (-2 \times 1) + (4 \times 2) + (-8 \times -1) \\ (4 \times 1) + (-1 \times 2) + (-5 \times -1) \end{bmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -\frac{1}{14} \begin{pmatrix} -6 - 4 - 4 \\ -2 + 8 + 8 \\ 4 - 2 + 5 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -\frac{1}{14} \begin{pmatrix} -14 \\ 14 \\ 7 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{bmatrix} \left(\frac{-14}{-14}\right) \\ \left(\frac{14}{-14}\right) \\ \left(\frac{7}{-14}\right) \end{bmatrix}$$

$$\rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -\frac{1}{2} \end{pmatrix}$$

$$\therefore x = 1, y = -1 \text{ and } z = -\frac{1}{2}.$$

PROVERBS 16V3